

ON FOURIER SERIES OF I -FUNCTIONS OF r -VARIABLES

P. C. SREENIVAS¹ AND M. SUNITHA²

¹ Department of Mathematics, Payyanur College,
Payyanur, Kannur Dist, Kerala- 670327, India

² Department of Mathematics,
Co-operative Arts and Science College,
Madayi, Kannur Dist, Kerala -670358, India

Abstract

The object of this paper is to evaluate some integrals involving the I -function of r -variables and employ them to obtain some Fourier Sine Series for I -function of r -variables. These results are useful in solving certain problems of Applied Mathematics and Engineering. On specializing the parameters the result can be reduced to integrals involving H -function of r -variables and in particular H -function of 2-variables. The corresponding Fourier Sine Series for these functions can also be derived which reduces to the result proved by K. L. Choudhary [1, p.53].

1. Introduction

Notations used :

$(a_p) = {}_1(a_j)_p$ stands for a_1, a_2, \dots, a_p

${}_1(a_j; \alpha_j)_p$ stands for $(a_1; \alpha_1), (a_2; \alpha_2), \dots, (a_p; \alpha_p)$.

Key Words : I -function of several complex variables, Multivariable H -functions, Fourier Series, Fourier Sine Series.

2000 AMS Subject Classification : 45 A 05.

© <http://www.ascent-journals.com>

${}_1(a_j; \alpha_j, A_j)_p$ stands for $(a_1; \alpha_1, A_1), (a_2; \alpha_2, A_2), \dots, (a_p; \alpha_p, A_p)$.

${}_1(a_j; \alpha_j, A_j; 1)_p$ stands for $(a_1; \alpha_1, A_1; 1), (a_2; \alpha_2, A_2; 1), \dots, (a_p; \alpha_p, A_p; 1)$.

The generalized Fox's H -function, namely I -function of r -variables introduced by Prathima, et al. [2, p.38] is defined and represented in the following manner:

$$\begin{aligned}
 I[z_1, \dots, z_r] &= I_{P,Q;p_1,q_1;\dots;p_r,q_r}^{0,N;m_1,n_1;\dots;m_r,n_r} \\
 &\left[\begin{array}{l} z_1 \\ \dots \\ z_r \end{array} \middle| \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}; \gamma_j^{(1)}, C_j^{(1)})_{p_1}, \dots; {}_1(c_j^{(r)}; \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}; \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}; \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{array} \right] \\
 &= \frac{1}{(2\pi\omega)^r} \int_{L_1} \dots \int_{L_r} \theta_1(s_1) \dots \theta_r(s_r) \phi(s_1, \dots, s_r) z_1^{s_1} \dots z_r^{s_r} ds_1 \dots ds_r, \quad (1.1)
 \end{aligned}$$

where $\phi(s_1, \dots, s_r)$ and $\theta_i(s_i), i = 1, 2, \dots, r$ are given by,

$$\phi(s_1, \dots, s_r) = \frac{\prod_{j=1}^N \Gamma^{A_j} \left(1 - a_j + \sum_{i=1}^r a_j^{(i)} s_i \right)}{\prod_{j=1}^Q \Gamma^{B_j} \left(1 - b_j + \sum_{i=1}^r \beta_j^{(i)} s_i \right) \prod_{j=N+1}^P \Gamma^{A_j} \left(a_j - \sum_{i=1}^r \alpha_j^{(i)} s_i \right)}, \quad (1.2)$$

$$\theta_i(s_i) = \frac{\prod_{j=1}^{m_i} \Gamma^{D_j^{(i)}} (d_j^{(i)} - \delta_j^{(i)} s_i) \prod_{j=1}^{n_i} \Gamma^{C_j^{(i)}} (1 - c_j^{(i)} + \gamma_j^{(i)} s_i)}{\prod_{j=m_i+1}^{q_i} \Gamma^{D_j^{(i)}} (1 - d_j^{(i)} + \delta_j^{(i)} s_i) \prod_{j=n_i+1}^{p_i} \Gamma^{C_j^{(i)}} (c_j^{(i)} - \gamma_j^{(i)} s_i)}. \quad (1.3)$$

Also, $z_i \neq 0$ ($i = 1, \dots, r$), $\omega = \sqrt{-1}$, m_j, n_j, p_j, q_j ($j = 1, \dots, r$), N, P, Q are non-negative integers such that $0 \leq N \leq P$, $Q \geq 0$, $0 \leq m_j \leq q_j$, $0 \leq n_j \leq p_j$ ($j = 1, 2, \dots, r$) (not all zero simultaneously). $\alpha_j^{(i)}$ ($j = 1, 2, \dots, P, i = 1, 2, \dots, r$), $\beta_j^{(i)}$ ($j = 1, 2, \dots, Q, i = 1, 2, \dots, r$), $\gamma_j^{(i)}$ ($j = 1, 2, \dots, p_i, i = 1, 2, \dots, r$) and $\delta_j^{(i)}$ ($j = 1, 2, \dots, q_i, i = 1, 2, \dots, r$) are positive numbers. a_j ($j = 1, 2, \dots, P$), b_j ($j = 1, 2, \dots, Q$), $c_j^{(i)}$ ($j = 1, 2, \dots, p_i, i = 1, 2, \dots, r$) and $d_j^{(i)}$ ($j = 1, 2, \dots, q_i, i = 1, 2, \dots, r$) are complex numbers. The exponents A_j ($j = 1, 2, \dots, P$), B_j ($j = 1, 2, \dots, Q$), $C_j^{(i)}$ ($j = 1, 2, \dots, p_i, i = 1, 2, \dots, r$) and $D_j^{(i)}$ ($j = 1, 2, \dots, q_i, i = 1, 2, \dots, r$) of various gamma functions may take non integer values. The I -function of r variables is analytic if

$$\Psi_i = \sum_{j=1}^P A_j \alpha_j^{(i)} - \sum_{j=1}^Q B_j \beta_j^{(i)} + \sum_{j=1}^{p_i} C_j^{(i)} \gamma_j^{(i)} - \sum_{j=1}^{q_i} D_j^{(i)} \delta_j^{(i)} \leq 0, \quad i = 1, 2, \dots, r.$$

The integral (1.1) converges absolutely if $|arg(z_i)| < \frac{1}{2}\Delta_i\pi, i = 1, 2, \dots, r$ where

$$\begin{aligned} \Delta_i = & - \sum_{j=n+1}^P A_j \alpha_j^{(i)} - \sum_{j=1}^Q B_j \beta_j^{(i)} + \sum_{j=1}^{m_i} D_j^{(i)} \delta_j^{(i)} - \sum_{j=m_i+1}^{q_i} D_j^{(i)} \delta_j^{(i)} \\ & + \sum_{j=1}^{n_i} C_j^{(i)} \gamma_j^{(i)} - \sum_{j=n_i+1}^{p_i} C_j^{(i)} \gamma_j^{(i)} > 0. \end{aligned}$$

Hann D. B. D. E. [2, p. 73]

$$\int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} dx = \frac{\Gamma(u)\Gamma(v)}{\Gamma(u+v)} e^{iu\frac{\pi}{2}} \tag{1.4}$$

Re $u > 0, \text{Re } v > 0.$

Lryzhk I. M. and Gradshtejn I. S. (3, p. 490]

$$\int_0^{\pi/2} e^{4mix} \sin 4nxdx = \begin{cases} 0, & \text{if } m \neq n, m = n = 0 \\ \frac{\pi i}{4}, & \text{if } m = n \neq 0. \end{cases} \tag{1.5}$$

2. The Integrals Involving I-functions of r-variables

$$\begin{aligned} (1) \quad & \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q;p_1,q_1;\dots;p_r,q_r}^{0,N;m_1,n_1;\dots;m_r,n_r} \\ & \left[\begin{array}{l} z_1 (\sin x \cos x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r (\sin x \cos x)^{h_r} e^{2h_r x i} \end{array} \right. \\ & \left. \begin{array}{l} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx \\ & = e^{iu\frac{\pi}{2}} I_{P+2,Q+1;p_1,q_1;\dots;p_r,q_r}^{0,N+2;m_1,n_1;\dots;m_r,n_r} \\ & \left[\begin{array}{l} z_1 e^{ih_1\frac{\pi}{2}} \left| \begin{array}{l} (1-u; h_1, \dots, h_r; 1), (1-v; h_1, \dots, h_r; 1), \\ \vdots \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \end{array} \right. \\ 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ (1-u-v; 2h_1, \dots, 2h_r; 1) : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] \tag{2.1} \\ & \text{Re} \left(u + \sum_{i=1}^r h_i \frac{d_j^{(i)}}{\delta_j^{(i)}} \right) > 0, \quad \text{Re} \left(v + \sum_{i=1}^r h_i \frac{d_j^{(i)}}{\delta_j^{(i)}} \right) > 0, \quad j = 1, 2, \dots, m_i. \end{aligned}$$

Proof:

$$\begin{aligned}
& \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q}^{0,N;m_1,n_1;\dots;m_r,n_r} \\
& \left[\begin{array}{c} z_1 (\sin x \cos x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r (\sin x \cos x)^{h_r} e^{2h_r x i} \end{array} \right. \\
& \left. \begin{array}{c} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx \\
& = \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} \left[\left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots, \theta_r(s_r) \right. \\
& \left. (z_1 (\cos x \sin x)^{h_1} e^{2h_1 i x})^{s_1} \dots (z_r (\cos x \sin x)^{h_r} e^{2h_r i x})^{s_r} ds_1 \dots ds_r \right] dx.
\end{aligned}$$

Changing the order of integration

$$\begin{aligned}
& = \left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots \theta_r(s_r) z_1^{s_1} \dots z_r^{s_r} \\
& \left[\int_0^{\pi/2} (\sin x)^{u + \sum_{i=1}^r h_i s_i - 1} (\cos x)^{v + \sum_{i=1}^r h_i s_i - 1} e^{i(u+v + \sum_{i=1}^r 2h_i s_i)x} dx \right] ds_1 \dots ds_r.
\end{aligned}$$

Solving the inner integral using (1.4),

$$\begin{aligned}
& = \left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots \theta_r(s_r) z_1^{s_1} \dots z_r^{s_r} \\
& \frac{\Gamma\left(u + \sum_{i=1}^r h_i s_i\right) \Gamma\left(v + \sum_{i=1}^r h_i s_i\right)}{\Gamma\left(u + v + \sum_{i=1}^r 2h_i s_i\right)} e^{i\left(u + \sum_{i=1}^r h_i s_i\right) \frac{\pi}{2}} ds_1 \dots ds_r.
\end{aligned}$$

From which (2.1) is obtained by using (1.1).

$$\begin{aligned}
 (2) \quad & \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{l} z_1 (\cos x)^{h_1} e^{h_1 x i} \\ \vdots \\ z_r (\cos x)^{h_r} e^{h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx \\
 & = \Gamma(u) e^{iu \frac{\pi}{2}} I_{P+1,Q+1;p_1,q_1;\dots,p_r,q_r}^{0,N+1;m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{l} z_1 \left| \begin{array}{l} (1-v; h_1, \dots, h_r; 1), \\ \vdots \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \end{array} \right. \\ {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ (1-u-v; h_1, \dots, h_r; 1) : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] \quad (2.2)
 \end{aligned}$$

$$\operatorname{Re} \left(v + \sum_{i=1}^r h_i \frac{d_j^{(i)}}{\delta_j^{(i)}} \right) > 0, \quad j = 1, 2, \dots, m_i.$$

Proof:

$$\begin{aligned}
 & \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{l} z_1 (\cos x)^{h_1} e^{h_1 x i} \\ \vdots \\ z_r (\cos x)^{h_r} e^{h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx \\
 & = \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} \left[\left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots, \theta_r(s_r) \right. \\
 & \left. (z_1 (\cos x)^{h_1} e^{h_1 i x})^{s_1} \dots (z_r (\cos x)^{h_r} e^{h_r i x})^{s_r} ds_1 \dots ds_r \right] dx.
 \end{aligned}$$

Changing the order of integration

$$= \left(\frac{1}{2\pi i}\right)^r \int_{L_1} \cdots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \cdots \theta_r(s_r) z_1^{s_1} \cdots z_r^{s_r} \left[\int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v+\sum_{i=1}^r h_i s_i - 1} e^{i\left(u+v+\sum_{i=1}^r h_i s_i\right)x} dx \right] ds_1 \cdots ds_r.$$

Solving the inner integral using (1.4),

$$= \left(\frac{1}{2\pi i}\right)^r \int_{L_1} \cdots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \cdots \theta_r(s_r) z_1^{s_1} \cdots z_r^{s_r} \frac{\Gamma(u)\Gamma\left(v+\sum_{i=1}^r h_i s_i\right)}{\Gamma\left(u+v+\sum_{i=1}^r h_i s_i\right)} e^{iu\frac{\pi}{2}} ds_1 \cdots ds_r.$$

From which (2.2) is obtained by using (1.1).

$$(3) \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \left[\begin{matrix} z_1(\sin x)^{h_1} e^{h_1 x i} \\ \vdots \\ z_r(\sin x)^{h_r} e^{h_r x i} \\ 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{matrix} \right] dx$$

$$= \Gamma(v) e^{iu\frac{\pi}{2}} I_{P+1,Q+1;p_1,q_1;\dots,p_r,q_r}^{0,N+1;m_1,n_1;\dots,m_r,n_r} \left[\begin{matrix} z_1 e^{ih_1\frac{\pi}{2}} \left| \begin{matrix} (1-u; h_1, \dots, h_r; 1), \\ \vdots \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \\ 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}; C_j^{(r)})_{p_r} \end{matrix} \right. \\ (1-u-v; h_1, \dots, h_r; 1) : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{matrix} \right] \tag{2.3}$$

$$Re \left(u + \sum_{i=1}^r h_i \frac{d_j^{(i)}}{\delta_j^{(i)}} \right) > 0, \quad j = 1, 2, \dots, m_i.$$

Proof:

$$\begin{aligned}
& \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} I_{P,Q}^{0,N:m_1,n_1;\dots;m_r,n_r} \\
& \left[\begin{array}{c} z_1 (\sin x)^{h_1} e^{h_1 x i} \\ \vdots \\ z_r (\sin x)^{h_r} e^{h_r x i} \end{array} \right. \\
& \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx \\
& = \int_0^{\pi/2} (\sin x)^{u-1} (\cos x)^{v-1} e^{i(u+v)x} \left[\left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots \theta_r(s_r) \right. \\
& \left. (z_1 (\sin x)^{h_1} e^{h_1 i x})^{s_1} \dots (z_r (\sin x)^{h_r} e^{h_r i x})^{s_r} ds_1 \dots ds_r \right] dx.
\end{aligned}$$

Changing the order of integration

$$\begin{aligned}
& = \left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots \theta_r(s_r) z_1^{s_1} \dots z_r^{s_r} \\
& \left[\int_0^{\pi/2} (\sin x)^{u + \sum_{i=1}^r h_i s_i - 1} (\cos x)^{v-1} e^{i \left(u + v + \sum_{i=1}^r h_i s_i \right) x} dx \right] ds_1 \dots ds_r.
\end{aligned}$$

Solving the inner integral using (1.4),

$$\begin{aligned}
& = \left(\frac{1}{2\pi i} \right)^r \int_{L_1} \dots \int_{L_r} \phi(s_1, \dots, s_r) \theta_1(s_1) \dots \theta_r(s_r) z_1^{s_1} \dots z_r^{s_r} \\
& \frac{\Gamma \left(u + \sum_{i=1}^r h_i s_i \right) \Gamma(v)}{\Gamma \left(u + v + \sum_{i=1}^r h_i s_i \right)} e^{i \left(u + \sum_{i=1}^r h_i s_i \right) \frac{\pi}{2}} ds_1 \dots ds_r.
\end{aligned}$$

From which (2.3) is obtained by using (1.1).

3. The Fourier Sine Series Involving I -functions of r -variables

$$\begin{aligned}
 (1) \quad & (\sin x)^{4u-1} (\cos x)^{4v-1} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{c} z_1 (\sin x \cos x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r (\sin x \cos x)^{h_r} e^{2h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}; \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}; \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}; \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}; \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{array} \right] \\
 & = \frac{4}{\pi i} \sum_{v=0}^{\infty} \left\{ I_{P+2,Q+1;p_1,q_1;\dots,p_r,q_r}^{0,N+2;m_1,n_1;\dots,m_r,n_r} \right. \\
 & \left. \left[\begin{array}{l} z_1 e^{ih_1 \frac{\pi}{2}} \left| \begin{array}{l} (1-4u; h_1, \dots, h_r; 1), (1-4v; h_1, \dots, h_r; 1), \\ \vdots \\ z_r e^{ih_r \frac{\pi}{2}} \left| \begin{array}{l} {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \\ {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}; \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}; \gamma_j^{(r)}; C_j^{(r)})_{p_r} \end{array} \right. \end{array} \right. \right. \\
 & \left. \left. (1-4u-4v; 2h_1, \dots, 2h_r; 1) : {}_1(d_j^{(1)}; \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}; \delta_j^{(r)}; D_j^{(r)})_{q_r} \right. \right] \left. \right\} \sin 4(u+v)x \\
 & \tag{3.1}
 \end{aligned}$$

Proof : Consider

$$\begin{aligned}
 f(x) &= (\sin x)^{4u-1} (\cos x)^{4v-1} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{c} z_1 (\sin x \cos x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r (\sin x \cos x)^{h_r} e^{2h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}; \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}; \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}; \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}; \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{array} \right] \\
 & = \sum_{n=0}^{\infty} c_n \sin 4(u+n)x, \quad 0 < x < \frac{\pi}{2}. \tag{3.2}
 \end{aligned}$$

Multiplying both sides by $e^{4(u+v)xi}$ and integrating with respect to x from 0 to $\frac{\pi}{2}$,

$$\int_0^{\pi/2} (\sin x)^{4u-1} (\cos x)^{4v-1} e^{4(u+v)xi} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \left[\begin{matrix} z_1 (\sin x \cos x)^{h_1} e^{2h_1xi} \\ \vdots \\ z_r (\sin x \cos x)^{h_r} e^{2h_rxi} \end{matrix} \middle| \begin{matrix} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{matrix} \right] dx$$

$$= \int_0^{\pi/2} e^{4(u+v)xi} \sum_{n=0}^{\infty} c_n \sin 4(u+n)x dx.$$

Changing the order of summation and integration the integral is equal to

$$\sum_{n=0}^{\infty} c_n \int_0^{\pi/2} e^{4(u+v)xi} \sin 4(u+n)x dx.$$

On evaluating the integral using (1.5) it takes the value $c_v \frac{\pi}{4} i$ from which (3.1) is obtained by using (2.1) and (3.2).

$$(2) \quad (\sin x)^{4u-1} (\cos x)^{4v-1} I_{P,Q;p_1,q_1;\dots,p_r,q_r}^{0,N;m_1,n_1;\dots,m_r,n_r} \left[\begin{matrix} z_1 (\cos x)^{h_1} e^{2h_1xi} \\ \vdots \\ z_r (\cos x)^{h_r} e^{2h_rxi} \end{matrix} \middle| \begin{matrix} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{matrix} \right]$$

$$= \frac{4}{\pi i} \Gamma(4u) \sum_{v=0}^{\infty} \left\{ I_{P+1,Q+1;p_1,q_1;\dots,p_r,q_r}^{0,N+1;m_1,n_1;\dots,m_r,n_r} \left[\begin{matrix} z_1 \left| \begin{matrix} (1-4v; h_1, \dots, h_r; 1), \\ \vdots \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \end{matrix} \right. \right. \\ \left. \left. \begin{matrix} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ (1-4u-4v; h_1, \dots, h_r; 1) : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{matrix} \right] \right\} \sin 4(u+v)x. \tag{3.3}$$

Proof : Let

$$\begin{aligned}
 f(x) &= (\sin x)^{4u-1} (\cos x)^{4v-1} I_{P,Q:p_1,q_1;\dots,p_r,q_r}^{0,N:m_1,n_1;\dots,m_r,n_r} \\
 &\left[\begin{array}{l} z_1(x \cos x)^{h_1} e^{2h_1xi} \\ \vdots \\ z_r(\cos x)^{h_r} e^{2h_rxi} \end{array} \right] \\
 &\left[\begin{array}{l} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{array} \right] \\
 &= \sum_{n=0}^{\infty} c_n \sin 4(u+n)x, \quad 0 < x < \frac{\pi}{2}. \tag{3.4}
 \end{aligned}$$

Multiplying both sides by $e^{4(u+v)xi}$ and integrating with respect to x from 0 to $\frac{\pi}{2}$,

$$\begin{aligned}
 &\int_0^{\pi/2} (\sin x)^{4u-1} (\cos x)^{4v-1} e^{4(u+v)xi} I_{P,Q:p_1,q_1;\dots,p_r,q_r}^{0,N:m_1,n_1;\dots,m_r,n_r} \\
 &\left[\begin{array}{l} z_1(\cos x)^{h_1} e^{2h_1xi} \\ \vdots \\ z_r(x \cos x)^{h_r} e^{2h_rxi} \end{array} \right] \\
 &\left[\begin{array}{l} 1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : 1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; 1(c_j^{(r)}, \gamma_j^{(r)}; C_j^{(r)})_{p_r} \\ 1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : 1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; 1(d_j^{(r)}, \delta_j^{(r)}; D_j^{(r)})_{q_r} \end{array} \right] dx \\
 &= \int_0^{\pi/2} e^{4(u+v)xi} \sum_{n=0}^{\infty} c_n \sin 4(u+n)x dx.
 \end{aligned}$$

Changing the order of summation and integration the integral is equal to

$$\sum_{n=0}^{\infty} c_n \int_0^{\pi/2} e^{4(u+v)xi} \sin 4(u+n)x dx.$$

Evaluating the integral using (1.5) it takes the value $c_v \frac{\pi}{4} i$ from which (3.3) is obtained by using (2.2) and (3.4).

$$\begin{aligned}
 (3) \quad & (\sin x)^{4u-1}(\cos x)^{4v-1} I_{P,Q:p_1,q_1;\dots,p_r,q_r}^{0,N:m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{c} z_1(x \cos x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r(x \cos x)^{h_r} e^{2h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] \\
 & = \frac{4}{\pi i} \Gamma(4v) \sum_{v=0}^{\infty} \left\{ I_{P+1,Q+1:p_1,q_1;\dots,p_r,q_r}^{0,N+1:m_1,n_1;\dots,m_r,n_r} \right. \\
 & \left. \left[\begin{array}{c} z_1 e^{i h_1 \frac{\pi}{2}} \\ \vdots \\ z_r e^{i h_r \frac{\pi}{2}} \end{array} \right. \left. \begin{array}{l} (1 - 4u; h_1, \dots, h_r; 1), \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q, \\ {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ (1 - 4u - 4v; h_1, \dots, h_r; 1) : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] \right\} \sin 4(u + v)x. \tag{3.5}
 \end{aligned}$$

Proof : Let

$$\begin{aligned}
 f(x) &= (\sin x)^{4u-1}(\cos x)^{4v-1} I_{P,Q:p_1,q_1;\dots,p_r,q_r}^{0,N:m_1,n_1;\dots,m_r,n_r} \\
 & \left[\begin{array}{c} z_1(\sin x)^{h_1} e^{2h_1 x i} \\ \vdots \\ z_r(\sin x)^{h_r} e^{2h_r x i} \end{array} \right. \\
 & \left. \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] \\
 & = \sum_{n=0}^{\infty} c_n \sin 4(u + n)x, \quad 0 < x < \frac{\pi}{2}. \tag{3.6}
 \end{aligned}$$

Multiplying both sides by $e^{4(u+v)xi}$ and integrating with respect to x from 0 to $\frac{\pi}{2}$,

$$\int_0^{\pi/2} (\sin x)^{4u-1} (\cos x)^{4v-1} e^{4(u+v)xi} I_{P,Q:p_1,q_1;\dots,p_r,q_r}^{0,N:m_1,n_1;\dots,m_r,n_r} \left[\begin{array}{l} z_1(\sin x)^{h_1} e^{2h_1xi} \\ \vdots \\ z_r(\sin x)^{h_r} e^{2h_rxi} \end{array} \middle| \begin{array}{l} {}_1(a_j; \alpha_j^{(1)}, \dots, \alpha_j^{(r)}; A_j)_P : {}_1(c_j^{(1)}, \gamma_j^{(1)}, C_j^{(1)})_{p_1}; \dots; {}_1(c_j^{(r)}, \gamma_j^{(r)}, C_j^{(r)})_{p_r} \\ {}_1(b_j; \beta_j^{(1)}, \dots, \beta_j^{(r)}; B_j)_Q : {}_1(d_j^{(1)}, \delta_j^{(1)}, D_j^{(1)})_{q_1}; \dots; {}_1(d_j^{(r)}, \delta_j^{(r)}, D_j^{(r)})_{q_r} \end{array} \right] dx$$

$$= \int_0^{\pi/2} e^{4(u+v)xi} \sum_{n=0}^{\infty} c_n \sin 4(u+n)x dx.$$

Changing the order of summation and integration the integral is equal to

$$\sum_{n=0}^{\infty} c_n \int_0^{\pi/2} e^{4(u+v)xi} \sin 4(u+n)x dx.$$

Evaluating the integral using (1.5) it takes the value $c_v \frac{\pi}{4} i$ from which (3.3) is obtained by using (2.3) and (3.6).

Special Cases :

1. In the results, when the third variable equal to 1, it reduces to H -function of r -variables.
2. When $r = 2$, all results will reduce to I -function of 2-variables.
3. When $r = 2$ and the third parameter equal to 1, it reduces to H -function of 2-variables.
4. Put $N = P = Q = 0$ and take $r = 1$, then all results reduce to product of r I -functions of 1- variables.
5. When $r = 1$, all results will reduce to I -function of 1-variable.
6. When $r = 1$ and the third parameter equal to 1, it reduces to the result proved by K. L. Choudhary [1].

References

- [1] Choudhary K. L., Fourier series of Fox's H -function, The Mathematics Education, IX(3) (Sept 1975).
- [2] Hann D. B. D. E., Nouvelles tables D'integrals defines, Hapner Publishing Co., NewYork, (1957).
- [3] Lryzhk I. M. and Gradshtejn I. S., Tables of Series, products and integrals., State Publishing of Physical and Mathematical Literature, Moscow, (1963).
- [4] Prathima J. Investigations in Integral Transforms Involving I -Functions of ' r ' Complex Variables, Ph.D. Thesis, Sri Chandrashekarendra Saraswathi Viswa Mahavidyalaya, Kanchipuram (2014).