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COMMON FIXED POINT THEOREM IN COMPLEX VALUED METRIC SPACE UNDER WEAKER CONDITIONS

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Abstract

In this paper, a common fixed point result for two pairs of weakly compatible mappings in complex valued metric space has been proved using a weaker condition called property $(E.A)$. Our result improves the results of Ajam et al [3] in the sense that the completeness of the space has been relaxed and a weaker condition of property $(E.A)$ has been used.

1 Introduction

Azam et al. [3] established the existence of common fixed points of a pair of mappings satisfying a contractive condition by introducing the notion of complex-valued metric space. Then the complex-valued normed spaces and complex-valued Hilbert spaces were defined on complex-valued metric spaces. Azam et al [3] and Bhatt et al [4] used the rational inequality in a complex-valued metric space as contractive condition.

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The concept of property $(E.A)$ in a complex-valued metric space was introduced by Verma and Pathak [7] to prove some common fixed point results for a quadruple of self-mappings satisfying a contractive condition of ‘max’ type. Their results generalize various theorems of ordinary metric spaces.

Ahmad et al [2] established some common fixed results for mappings fulfilling rational expressions on a closed ball in complex valued metric spaces, while Rafiq et al [6] proved some common fixed point theorems of weakly compatible mappings in complex valued metric spaces.

In this paper, we improve the results of Ajam et al [3] in the sense that the completeness of the space has been relaxed and a weaker condition of property $(E.A)$ has been used.

2 Preliminaries.

The following definitions are introduced by Azam et al [3]

Let \mathbb{C} be the set of complex numbers and $z_1, z_2 \in \mathbb{C}$.

Define a partial order \lesssim on \mathbb{C} as follows:

$z_1 \lesssim z_2$ if and only if

$$\operatorname{Re}(z_1) \leq \operatorname{Re}(z_2), \operatorname{Im}(z_1) \leq \operatorname{Im}(z_2)$$

Therefore one can infer $z_1 \lesssim z_2$ if any one of the following conditions is satisfied:

- (i) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2), \operatorname{Im}(z_1) < \operatorname{Im}(z_2)$,
- (ii) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2), \operatorname{Im}(z_1) = \operatorname{Im}(z_2)$,
- (iii) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2), \operatorname{Im}(z_1) < \operatorname{Im}(z_2)$,
- (iv) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2), \operatorname{Im}(z_1) = \operatorname{Im}(z_2)$

From (i), (ii) and (iii) we have $|z_1| < |z_2|$ and from (iv) we have $|z_1| = |z_2|$.

We write $z_1 \prec z_2$ only if (iii) is satisfied.

Also

$$\begin{aligned} 0 &\lesssim z_1 \lesssim z_2 \Rightarrow |z_1| \leq |z_2| \\ z_1 &\lesssim z_2, z_2 \prec z_3 \Rightarrow z_1 \prec z_3 \end{aligned}$$

Definition 2.1 [3] Let X be a nonempty set whereas \mathbb{C} be the set of complex numbers.

Suppose that the mapping $d : X \times X \rightarrow \mathbb{C}$, satisfies:

- (1) $0 \lesssim d(x, y)$, for all $x, y \in X$ and $d(x, y) = 0$ if and only if $x = y$;

- (2) $d(x, y) = d(y, x)$ for all $x, y \in X$;
 (3) $d(x, y) \lesssim d(x, z) + d(z, y)$, for all $x, y, z \in X$.

Then d is called a complex valued metric on X , and (X, d) is called a complex valued metric space.

Example 2.1 Let X be a nonempty set.

Define the mapping $d : X \times X \rightarrow \mathbb{C}$ by

$$d(x, y) = \frac{|x - y|}{x^2 + y^2} e^{ik}, k \in \mathbb{R}, x, y \in X.$$

Then (X, d) is a complex valued metric space.

A point $x \in X$ is called interior point of a set $A \subseteq X$ whenever there exists $0 \prec r \in \mathbb{C}$ such that

$$B(x, r) = \{y \in X : d(x, y) \prec r\} \subseteq A$$

A point $x \in X$ is called a limit point of A whenever for every $0 \prec r \in \mathbb{C}$,

$$B(x, r) \cap (A - X) \neq \phi$$

A is called open whenever each element of A is an interior point of A . A subset $B \subseteq X$ is called closed whenever each limit point of B belongs to B .

The family

$$F = \{B(x, r) : x \in X, 0 \prec r\}$$

is a sub-basis for a Hausdorff topology τ on X .

Aamri and Moutawakil [1] developed several common fixed point theorems for mappings having the property $(E.A)$ on a metric space under rigorous contractive conditions.

Definition 2.2 [1] A pair of self-mappings f, g defined on a metric space (X, d) is said to satisfy the property $(E.A.)$ if there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} f x_n = \lim_{n \rightarrow +\infty} g x_n = t \in X.$$

Definition 2.3 [4] A pair of self-mappings $A, S : X \rightarrow X$ is called weakly-compatible if they commute at their coincidence points. That is, if there be a point $u \in X$ such that $Au = Su$, then $ASu = SAu$, for each $u \in X$.

In complex valued metric space, Verma and Pathak [7] defined property $(E.A)$ as follows:

Definition 2.4 [7] Let $A, S : X \rightarrow X$ be two self-maps of a complex-valued metric space (X, d) . The pair (A, S) is said to satisfy property $(E.A)$, if there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} Ax_n = \lim_{n \rightarrow +\infty} Sx_n = t$$

for some $t \in X$.

Pathak et al [5] has that weakly compatibility and property $(E.A)$ are independent to each other (see Ex.2.5, Ex.2.6, Ex.2.7 of [5]).

3 Main Result.

Theorem 3.1 Let (X, d) be a complex valued metric space and mappings $f, g, S, T : X \rightarrow X$ satisfying:

$$(3.1.1) \quad S(X) \subset g(X) \text{ and } T(X) \subset f(X);$$

$$(3.1.2) \quad \forall x, y \in X,$$

$$d(Sx, Ty) \lesssim \lambda d(fx, gy) + \frac{\mu d(fx, Sx)d(gy, Ty)}{1 + d(fx, gy)}$$

where λ and μ are non-negative real numbers such that $\lambda + \mu < 1$,

(3.1.3) the pairs (S, f) and (T, g) are weakly compatible,

(3.1.4) one of the pairs (S, f) and (T, g) satisfies the property $(E.A)$.

If the range of one of the mappings f or g is a complete subspace of X , then mappings f, g, S and T have unique common fixed point in X .

Proof. If the pair (S, f) satisfies property $(E.A)$, then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} Sx_n = \lim_{n \rightarrow +\infty} fx_n = z,$$

Proof. If the pair (S, f) satisfies property $(E.A)$, then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} Sx_n = \lim_{n \rightarrow +\infty} fx_n = z,$$

for some $z \in X$.

Since $S(X) \subset g(X)$, there exists a sequence $\{y_n\}$ in X such that $gy_n = Sx_n$ for all

$n \in N$.

Which implies

$$\lim_{n \rightarrow +\infty} gy_n = \lim_{n \rightarrow +\infty} Sx_n = z$$

Now to show that

$$\lim_{n \rightarrow +\infty} Ty_n = z$$

From (3.1.2)

$$d(Sx_n, Ty_n) \lesssim \lambda d(fx_n, gy_n) + \frac{\mu d(fx_n, Sx_n) d(gy_n, Ty_n)}{1 + d(fx_n, gy_n)}$$

Taking $n \rightarrow \infty$, we get

$$d(z, Ty_n) \lesssim \lambda d(z, z) + \frac{\mu d(z, z) d(z, Ty_n)}{1 + d(z, z)}$$

Hence $\lim_{n \rightarrow +\infty} Ty_n = z$.

Similarly, If the pair (T, g) satisfies property $(E.A)$, then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} Tx_n = \lim_{n \rightarrow +\infty} gx_n = u,$$

for some $u \in X$.

Since $T(X) \subset f(X)$, there exists a sequence $\{y_n\}$ in X such that $fy_n = Tx_n$ for all $n \in N$.

Which implies

$$\lim_{n \rightarrow +\infty} fy_n = \lim_{n \rightarrow +\infty} Tx_n = u$$

Now to show that

$$\lim_{n \rightarrow +\infty} Sy_n = u$$

From (3.1.2)

$$d(Sy_n, Tx_n) \lesssim \lambda d(fy_n, gx_n) + \frac{\mu d(fy_n, Sy_n) d(gx_n, Tx_n)}{1 + d(fy_n, gx_n)}$$

Taking $n \rightarrow \infty$, we get

$$d(Sy_n, u) \lesssim \lambda d(u, u) + \frac{\mu d(u, Sy_n) d(u, u)}{1 + d(u, u)}$$

Hence $\lim_{n \rightarrow +\infty} Sy_n = u$.

Now suppose $f(X)$ is complete, then $fu = z$ for some $u \in X$.

Therefore

$$\lim_{n \rightarrow +\infty} Sx_n = \lim_{n \rightarrow +\infty} Ty_n = \lim_{n \rightarrow +\infty} fx_n = \lim_{n \rightarrow +\infty} gy_n = z = fu$$

Now we show that

$$Su = fu = z.$$

Using (3.1.2)

$$d(Su, Ty_n) \lesssim \lambda d(fu, gy_n) + \frac{\mu d(fu, Su) d(gy_n, Ty_n)}{1 + d(fu, gy_n)}$$

Let $n \rightarrow \infty$, then

$$d(Su, fu) \lesssim \lambda d(fu, fu) + \frac{\mu d(fu, Su) d(fu, fu)}{1 + d(fu, fu)}$$

Therefore

$$Su = fu = z$$

Hence u is a coincidence point of S and f .

Using the weak compatibility of the pair (S, f) , we have

$$Sfu = fSu$$

or

$$Sz = fz.$$

Since $S(X) \subset g(X)$, there exists w in X such that

$$Su = gw.$$

Therefore

$$Su = fu = gw = z$$

To show that w is the coincidence point of (T, g) i.e. $Tw = gw = z$. Using (3.1.2)

$$d(Su, Tw) \lesssim \lambda d(fu, gw) + \frac{\mu d(fu, Su) d(gw, Tw)}{1 + d(fu, gw)}$$

Which gives

$$d(z, Tw) \lesssim \lambda d(z, z) + \frac{\mu d(z, z) d(z, Tw)}{1 + d(z, z)}$$

i.e. $Tw = z$. Hence

$$Tw = gw = z.$$

Therefore w is a coincidence point of (T, g) .

Using weak compatibility of (T, g)

$$Tgw = gTw$$

or

$$Tz = gz$$

Therefore z is the common coincidence point of S, T, f and g .

To show z is the common fixed point of S, T, f and g .

Using (3.1.2)

$$d(Su, Tz) \lesssim \lambda d(fu, gz) + \frac{\mu d(fu, Su)d(gz, Tz)}{1 + d(fu, gz)}$$

Which gives

$$d(z, Tz) \lesssim \lambda d(z, Tz) + \frac{\mu d(z, z)d(gz, Tz)}{1 + d(z, Tz)}$$

i.e.

$$d(z, Tz) \lesssim \lambda d(z, Tz)$$

which is a contradiction as $0 < \lambda < 1$. Therefore $Tz = z$.

Hence

$$Sz = Tz = fz = gz.$$

i.e. z is the common fixed point of S, T, f and g .

Similar result follows when we assume that $g(X)$ is complete.

Now to show the uniqueness, let $v \in X$ be another common fixed point of S, T, f and g

i.e.

$$Sv = Tv = fv = gv = v.$$

Using (3.1.2),

$$d(Sz, Tv) \lesssim \lambda d(fz, gv) + \frac{\mu d(fz, Sz)d(gv, Tv)}{1 + d(fz, gv)}$$

which gives

$$d(z, v) \lesssim \lambda d(z, v) + \frac{\mu d(z, z)d(v, v)}{1 + d(z, v)}$$

i.e.

$$d(z, v) \lesssim \lambda d(z, v)$$

which is a contradiction as $0 < \lambda < 1$. Therefore $z = v$. for some $z \in X$.

Since $S(X) \subset g(X)$, there exists a sequence $\{y_n\}$ in X such that $gy_n = Sx_n$ for all $n \in N$.

Which implies

$$\lim_{n \rightarrow +\infty} gy_n = \lim_{n \rightarrow +\infty} Sx_n = z$$

Now to show that

$$\lim_{n \rightarrow +\infty} Ty_n = z$$

From (3.1.2)

$$d(Sx_n, Ty_n) \lesssim \lambda d(fx_n, gy_n) + \frac{\mu d(fx_n, Sx_n) d(gy_n, Ty_n)}{1 + d(fx_n, gy_n)}$$

Taking $n \rightarrow \infty$, we get

$$d(z, Ty_n) \lesssim \lambda d(z, z) + \frac{\mu d(z, z) d(z, Ty_n)}{1 + d(z, z)}$$

Hence $\lim_{n \rightarrow +\infty} Ty_n = z$.

Similarly, If the pair (T, g) satisfies property $(E.A)$, then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow +\infty} Tx_n = \lim_{n \rightarrow +\infty} gx_n = u,$$

for some $u \in X$.

Since $T(X) \subset f(X)$, there exists a sequence $\{y_n\}$ in X such that $fy_n = Tx_n$ for all $n \in N$.

Which implies

$$\lim_{n \rightarrow +\infty} fy_n = \lim_{n \rightarrow +\infty} Tx_n = u$$

Now to show that

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From (3.1.2)

$$d(Sy_n, Tx_n) \lesssim \lambda d(fy_n, gx_n) + \frac{\mu d(fy_n, Sy_n) d(gx_n, Tx_n)}{1 + d(fy_n, gx_n)}$$

Taking $n \rightarrow \infty$, we get

$$d(Sy_n, u) \lesssim \lambda d(u, u) + \frac{\mu d(u, Sy_n) d(u, u)}{1 + d(u, u)}$$

Hence $\lim_{n \rightarrow +\infty} Sy_n = u$.

Now suppose $f(X)$ is complete, then $fu = z$ for some $u \in X$.

Therefore

$$\lim_{n \rightarrow +\infty} Sx_n = \lim_{n \rightarrow +\infty} Ty_n = \lim_{n \rightarrow +\infty} fx_n = \lim_{n \rightarrow +\infty} gy_n = z = fu$$

Now we show that

$$Su = fu = z.$$

Using (3.1.2)

$$d(Su, Ty_n) \lesssim \lambda d(fu, gy_n) + \frac{\mu d(fu, Su) d(gy_n, Ty_n)}{1 + d(fu, gy_n)}$$

Let $n \rightarrow \infty$, then

$$d(Su, fu) \lesssim \lambda d(fu, fu) + \frac{\mu d(fu, Su) d(fu, fu)}{1 + d(fu, fu)}$$

Therefore

$$Su = fu = z$$

Hence u is a coincidence point of S and f .

Using the weak compatibility of the pair (S, f) , we have

$$Sfu = fSu$$

or

$$Sz = fz.$$

Since $S(X) \subset g(X)$, there exists w in X such that

$$Su = gw.$$

Therefore

$$Su = fu = gw = z$$

To show that w is the coincidence point of (T, g) i.e. $Tw = gw = z$.

Using (3.1.2)

$$d(Su, Tw) \lesssim \lambda d(fu, gw) + \frac{\mu d(fu, Su) d(gw, Tw)}{1 + d(fu, gw)}$$

Which gives

$$d(z, Tw) \lesssim \lambda d(z, z) + \frac{\mu d(z, z) d(z, Tw)}{1 + d(z, z)}$$

i.e. $Tw = z$. Hence

$$Tw = gw = z.$$

Therefore w is a coincidence point of (T, g) . Using weak compatibility of (T, g)

$$Tgw = gTw$$

or

$$Tz = gz$$

Therefore z is the common coincidence point of S, T, f and g .

To show z is the common fixed point of S, T, f and g .

Using (3.1.2)

$$d(Su, Tz) \lesssim \lambda d(fu, gz) + \frac{\mu d(fu, Su) d(gz, Tz)}{1 + d(fu, gz)}$$

Which gives

$$d(z, Tz) \lesssim \lambda d(z, Tz) + \frac{\mu d(z, z) d(gz, Tz)}{1 + d(z, Tz)}$$

i.e.

$$d(z, Tz) \lesssim \lambda d(z, Tz)$$

which is a contradiction as $0 < \lambda < 1$. Therefore $Tz = z$.

Hence

$$Sz = Tz = fz = gz.$$

i.e. z is the common fixed point of S, T, f and g .

Similar result follows when we assume that $g(X)$ is complete.

Now to show the uniqueness, let $v \in X$ be another common fixed point of S, T, f and g

i.e.

$$Sv = Tv = fv = gv = v.$$

Using (3.1.2),

$$d(Sz, Tv) \lesssim \lambda d(fz, gv) + \frac{\mu d(fz, Sz) d(gv, Tv)}{1 + d(fz, gv)}$$

which gives

$$d(z, v) \lesssim \lambda d(z, v) + \frac{\mu d(z, z) d(v, v)}{1 + d(z, v)}$$

i.e.

$$d(z, v) \lesssim \lambda d(z, v)$$

which is a contradiction as $0 < \lambda < 1$. Therefore $z = v$.

If we put $f = g = I$ in the Theorem 3.1, we get

Corollary 3.2 *Let (X, d) be a complex valued metric space and mappings $S, T : X \rightarrow X$ satisfying:*

$$(3.2.1) \quad S(X) \subset T(X) \text{ and } T(X) \subset f(X);$$

$$(3.2.2) \quad \forall x, y \in X,$$

$$d(Sx, Ty) \lesssim \lambda d(x, y) + \frac{\mu d(x, Sx)d(y, Ty)}{1 + d(x, y)}$$

where λ and μ are non-negative real numbers such that $\lambda + \mu < 1$,

$$(3.2.3) \quad \text{the pair } (S, T) \text{ is weakly compatible,}$$

$$(3.2.4) \quad \text{the pairs } (S, T) \text{ satisfies the property (E.A).}$$

If the range of one of the mappings $T(X)$ or $S(X)$ is a complete subspace of X , then mappings S and T have unique common fixed point in X .

If we put $f = g = I$ and $S = T$ in the Theorem 3.1, we get

Corollary 3.3 *Let (X, d) be a complex valued metric space and mapping $T : X \rightarrow X$ satisfying:*

$$d(Tx, Ty) \lesssim \lambda d(x, y) + \frac{\mu d(x, Tx)d(y, Ty)}{1 + d(x, y)}$$

$\forall x, y \in X$, where λ and μ are non-negative real numbers such that $\lambda + \mu < 1$.

If the range of the mapping $T(X)$ is a complete subspace of X , then the mapping T has a unique common fixed point in X .

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